

Module V: Torsion and Twist

1. Introduction to Torsion

Torsion refers to the **twisting of a structural member** (usually a shaft) when subjected to an **external torque**. The result is shear stress distributed over the cross-section and an angular deformation known as **twist**.

Applicable primarily to **circular shafts** — both solid and hollow — used in mechanical systems like shafts, axles, and helical springs.

2. Torsional Shear Stress

For a **circular shaft** subjected to torque T , the shear stress at a radius r is:

$$\tau = \frac{T r}{J}$$

Where:

- τ : Shear stress (Pa)
- T : Applied torque (N·m)
- r : Radial distance from center (m)
- J : Polar moment of inertia (m⁴)

For a solid circular shaft:

$$J = \frac{\pi d^4}{32}$$

For a hollow circular shaft:

$$J = \frac{\pi (d_o^4 - d_i^4)}{32}$$

3. Angle of Twist and Torsional Deformation

$$\theta = \frac{T L}{G J}$$

Where:

- θ : Angle of twist (in radians)
- L : Length of shaft

- GG: Shear modulus
- JJ: Polar moment of inertia

This relation helps calculate **twist per unit length** and total angular displacement under torque.

4. Stepped Shafts

For a shaft with **multiple segments** (different diameters or materials), the total twist is the **sum of individual twists**:

$$\theta_{\text{total}} = \sum (T_i L_i / G_i J_i) \quad \theta_{\text{total}} = \sum \left(\frac{T_i L_i}{G_i J_i} \right)$$

Boundary conditions (fixed, free, or loaded ends) must be applied appropriately to determine internal torque in each section.

5. Torsion in Shafts Fixed at Both Ends

When both ends of the shaft are **fixed** and subjected to external torque(s), compatibility of deformation must be enforced:

- The net angular displacement at the fixed ends is **zero**
 - Internal torques are solved using equilibrium and deformation compatibility
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6. Stresses and Deflection in Helical Springs

Helical springs under axial load behave as torsional elements.

a. Shear Stress:

$$\tau = \frac{8PD}{\pi d^3} \quad \tau = \frac{8PD}{\pi d^3}$$

Where:

- PP: Axial load
- DD: Mean coil diameter
- dd: Wire diameter

b. Deflection:

$$\delta = \frac{8 P D^3 n}{G d^4}$$

Where:

- n : Number of active coils

Helical springs are widely used for energy absorption and storage.